

# Lecture 1

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## 1 Optimization

Optimization is the science of making better decisions in unclear environments.

— Patrick L. Combettes

## 2 Overview

In this lecture, we introduce the Euclidean space, some basic identities and inequalities, and some basic concepts based on Euclidean space.

## 3 Euclidean space

The **Euclidean space**  $\mathcal{H}$  is a real finite dimensional vector space equipped with a scalar product  $\langle \cdot, \cdot \rangle : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}$ ,  $(x, y) \mapsto \langle x | y \rangle$ .

- **Properties of the scalar product**

- $\forall (x, y) \in \mathcal{H}^2, \langle x | y \rangle = \langle y | x \rangle$
- $\forall \alpha \in \mathbb{R}, \forall (x, y, z) \in \mathcal{H}^3, \langle \alpha x + y | z \rangle = \alpha \langle x | z \rangle + \langle y | z \rangle$
- $\forall x \in \mathcal{H} \setminus \{0\}, \langle x | x \rangle > 0$

A **norm** on  $\mathcal{H}$  is a function  $\|\cdot\|: \mathcal{H} \rightarrow \mathbb{R}$ ,  $x \mapsto \|x\|$  such that

- (i)  $\forall (x, y) \in \mathcal{H}^2, \|x + y\| \leq \|x\| + \|y\|$
- (ii)  $\forall \alpha \in \mathbb{R}, \forall x \in \mathcal{H}, \|\alpha x\| = |\alpha| \|x\|$
- (iii)  $\forall x \in \mathcal{H}, x = 0 \iff \|x\| = 0_{\mathcal{H}}$

The **default norm** of  $\mathcal{H}$  is the one associated with the scalar product:

$$\forall x \in \mathcal{H}, \|x\| = \sqrt{\langle x | x \rangle}, \quad (1)$$

which also gives rise to a **distance**

$$\forall (x, y) \in \mathcal{H}^2, d(x, y) = \|x - y\| = \sqrt{\langle x - y | x - y \rangle}. \quad (2)$$

## 4 Basic identities and inequalities

- **Cauchy–Schwarz:**  $\forall (x, y) \in \mathcal{H}^2, |\langle x | y \rangle| \leq \|x\|\|y\|$ . Moreover,  $|\langle x | y \rangle| = \|x\|\|y\| \iff \exists \alpha \in \mathbb{R}_+, x = \alpha y$
- $\forall (x, y) \in \mathcal{H}^2, \|x + y\|^2 = \|x\|^2 + 2\langle x | y \rangle + \|y\|^2$ .
- **Parallelogram identity:**  $\|x + y\|^2 + \|x - y\|^2 = 2\|x\|^2 + 2\|y\|^2$
- **Polarization identity:**  $\langle x | y \rangle = \frac{1}{4} [\|x + y\|^2 - \|x - y\|^2]$
- Let  $\alpha \in \mathbb{R}$ , then  $\|\alpha x + (1 - \alpha)y\|^2 = \alpha\|x\|^2 + (1 - \alpha)\|y\|^2 - \alpha(1 - \alpha)\|x - y\|^2$
- $\langle x | y \rangle \leq 0 \iff \forall \alpha \in [0, +\infty), \|x\| \leq \|x - \alpha y\| \iff \forall \alpha \in [0, 1], \|x\| \leq \|x - \alpha y\|$

## 5 Basic concepts

- Let  $x \in \mathcal{H}$  and  $\rho \in (0, +\infty)$ , the **ball** with center  $x$  and radius  $\rho$  is  $B(x; \rho) = \{y \in \mathcal{H} \mid \|x - y\| \leq \rho\}$ .
- Let  $C \in \mathcal{H}$ , then  $C$  is an **open set** if  $\forall x \in C, \exists \rho \in (0, +\infty), B(x; \rho) \subset C$ .  $C$  is a **closed set** if  $\mathcal{H} \setminus C$  is open.
- Take a sequence  $(x_n)_{n \in \mathbb{N}}$  in  $\mathcal{H}$  and a point  $x \in \mathcal{H}$ , then  $x_n$  **converges to**  $x$  if  $\|x_n - x\| \rightarrow 0$  as  $n \rightarrow \infty$ . In other words,  $\forall \rho \in (0, \infty), \exists N \in \mathbb{N}, \forall n \in \mathbb{N}, n \geq N \Rightarrow x_n \in B(x; \rho)$ .
- $C$  is a **closed set** means that for every sequence  $(x_n)_{n \in \mathbb{N}}$  in  $C$  that converges, say  $x_n \rightarrow x$ , then  $x \in C$ .

**Ex.** Let  $\mathcal{H} = \mathbb{R}, C = (0, 1), x_n = \frac{1}{1+n}$ , then  $x_n \rightarrow 0$  which is not in  $C$ , so  $C$  is not closed.

- A sequence  $(x_n)_{n \in \mathbb{N}}$  in  $\mathcal{H}$  converges if and only if it is a **Cauchy sequence**:  $\|x_n - x_m\| \rightarrow 0$ , as  $n, m \rightarrow \infty$ .
- **Operator**

– Let  $\mathcal{G}$  be an Euclidean space. The notation  $T : \mathcal{H} \rightarrow \mathcal{G}$  means that the operator (also called mapping)  $T$  maps every point  $x$  in  $\mathcal{H}$  to a point  $Tx$  in  $\mathcal{G}$ .

- $T$  is a **linear operator** if  $\forall \alpha \in \mathbb{R}, \forall (x, y) \in \mathcal{H}^2, T(\alpha x + y) = \alpha T x + T y$ .
  - $T$  is **continuous at**  $x \in \mathcal{H}$  if there is a sequence  $(x_n)_{n \in \mathbb{N}}$  in  $\mathcal{H}, x_n \rightarrow x \Rightarrow T x_n \rightarrow T x$ .  $T$  is **continuous** if this holds for every  $x \in \mathcal{H}$ .
- Let  $\mathbb{R}$  be the real line  $(-\infty, +\infty)$  and  $I \subset \mathbb{R}$ 
    - The **infimum** of  $I$  is the greatest lower bound of  $I$  ( $+\infty$  if  $I = \emptyset$ ).
      - \* A lower bound of  $I$  is a value  $a \in \mathbb{R}$  such that  $\forall x \in I, a \leq x$  and  $\forall \epsilon > 0, \exists x \in I$  such that  $x < a + \epsilon$ .
    - The **supremum** of  $I$  is the lowest upper bound of  $I$  ( $-\infty$  if  $I = \emptyset$ ).
      - \* An upper bound of  $I$  is a value  $b \in \mathbb{R}$  such that  $\forall x \in I, x \leq b$  and  $\forall \epsilon > 0, \exists x \in I$  such that  $x > b - \epsilon$ .

**Eg.**  $\inf(0, 1] = 0, \sup(0, 1] = 1$ .

    - If  $\inf I \in I$ , it is called a **minimum**, and it is denoted by  $\min I$ .
    - If  $\sup I \in I$ , it is called a **maximum**, and it is denoted by  $\max I$ .

**Eg.** Let  $I = \{y \mid y = e^{-x}\}$ , then  $\inf I = 0, \arg \min_x e^{-x}$  does not exist since  $0 \notin I$ .
- Let  $C$  be a subset of  $\mathcal{H}$ , and let  $f : \mathcal{H} \rightarrow [-\infty, +\infty], x \mapsto f(x)$ , then  $f(C) = \{f(x) \mid x \in C\} \subset [-\infty, +\infty]$ .
    - Notation:  $\inf f(C) = \inf_{x \in C} f(x), \sup f(C) = \sup_{x \in C} f(x)$
  - **Rules in**  $[-\infty, +\infty]$ :  $x + y$  is defined in a natural way, but  $(+\infty) - (+\infty)$  is not defined.  $\forall x \in (-\infty, +\infty], x + (+\infty) = +\infty$ .
  - Let  $C \subset \mathcal{H}$ ,
    - $C$  is a **vector subspace** if
      - i)  $C \neq \emptyset$ ;
      - ii)  $C + C = \{x + y \mid x \in C, y \in C\} \subset C$ ;
      - iii)  $\forall \alpha \in \mathbb{R}, \alpha C = \{\alpha x \mid x \in C\} \subset C$ .
    - $C$  is an **affine subspace** if  $\forall \alpha \in \mathbb{R}, \alpha C + (1 - \alpha)C = C$ .

**Eg.** Let  $u \in \mathcal{H} \setminus \{0_{\mathcal{H}}\}$  and  $\eta \in \mathbb{R}$ , then  $C = \{x \in \mathcal{H} \mid \langle x \mid u \rangle = \eta\}$  is called a **hyperplane**.

**Eg.** Let  $u \in \mathcal{H} \setminus \{0_{\mathcal{H}}\}$  and  $\eta \in \mathbb{R}$ , then  $C = \{x \in \mathcal{H} \mid \langle x \mid u \rangle \leq \eta\}$  is a **closed affine hal-space**, but not an affine space.

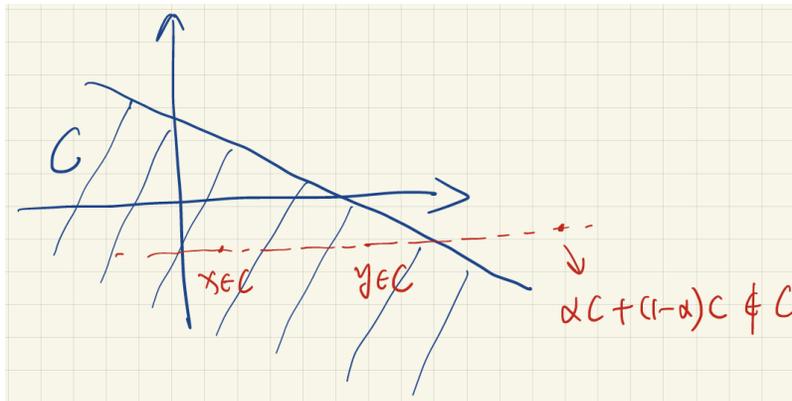


Figure 1: Illustration